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Perron Conditions for Stability of Linear Skew-Product Semiflows in Banach Spaces

In this paper we give necessary and sufficient conditions for uniform exponential stability of linear skew-product semiflows in Banach spaces. We give theorems of characterization for uniform exponential stability of linear skew-product semiflows in terms of boundedness of some operators acting on $C_{00}(\mathbb{R}_+, X)$, $C_b(\mathbb{R}_+, X)$, $C_c(\mathbb{R}_+, X)$ and $L^p(\mathbb{R}_+, X)$, respectively.

1. Linear skew-product semiflow

Let X be a Banach space, let (Θ, d) be a metric space and let $E = X \times \Theta$. We shall denote by $B(X)$ the Banach algebra of all bounded linear operators from X into itself. Throughout the paper, the norm on X and on $B(X)$ will be denoted by $\|\cdot\|$.

Definition 1.1 A continuous mapping $\sigma: \Theta \times \mathbb{R}_+ \rightarrow \Theta$ is said to be a **semiflow** on Θ , if it has the following properties:

- (i) $\sigma(\theta, 0) = \theta, \forall \theta \in \Theta$
- (ii) $\sigma(\theta, s+t) = \sigma(\sigma(\theta, s), t)$ for $\forall (\theta, s, t) \in \Theta \times \mathbb{R}_+^2$

Definition 1.2 A pair $\pi = (\Phi, \sigma)$ is called **linear skew-product semiflow** on $E = X \times \Theta$ if σ is a semiflow on Θ and $\Phi: \Theta \times \mathbb{R}_+ \rightarrow B(X)$ satisfies the following conditions:

- (i) $\Phi(\theta, 0) = I$, the identity operator on X , $\forall \theta \in \Theta$
- (ii) $\Phi(\theta, t+s) = \Phi(\sigma(\theta, s), t)\Phi(\theta, s)$ for all $(\theta, t, s) \in \Theta \times \mathbb{R}_+^2$ (the cocycle identity)
- (iii) $\exists M \geq 1$ and $\omega > 0$ such that $\|\Phi(\theta, t)\| \leq Me^{\omega t}$ for $\forall (\theta, t) \in \Theta \times \mathbb{R}_+$

If, in addition,

(iv) for every $(x, \theta) \in E$ the mapping $t \rightarrow \Phi(\theta, t)x$ is continuous then π is called a strongly continuous linear skew-product semiflow.

Remark 1.1 Statement (iii) is equivalent with the following

(iii)' there exist a nondecreasing function $f: \mathbb{R}_+ \rightarrow \mathbb{R}_+^*$ such that $\|\Phi(\theta, t)\| \leq f(t)$ for all $(\theta, t) \in \Theta \times \mathbb{R}_+$.

Example 1.1

Let X be a Banach space. We consider $C(\mathbb{R}_+, \mathbb{R})$ the space of all continuous function with the topology of uniform convergence on compact subsets on \mathbb{R}_+ . This space is metrizable with the metric

$$d(x, y) = \sum_{n=1}^{\infty} \frac{1}{2^n} \cdot \frac{d_n(x, y)}{1 + d_n(x, y)} \quad \text{where } d_n(x, y) = \sup_{t \in [0, n]} |x(t) - y(t)|.$$

On the Banach space X , we consider the nonautonomous differential equation

$$\dot{x}(t) = a(t)x(t), \quad t \geq 0$$

where $a: \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be a uniformly continuous function such that there exists

$\alpha := \lim_{t \rightarrow \infty} a(t) < \infty$. If we denote by $a_s(t) = a(t + s)$ and by $\Theta = \{\overline{a_s : s \in \mathbb{R}_+}\}$ then

$\sigma(\theta, t)(s) := \theta(t + s)$ is a semiflow on Θ , for $\Phi: \Theta \times \mathbb{R}_+ \rightarrow \mathcal{B}(X)$,

$\Phi(\theta, t)x = e^{\int_0^t \theta(\tau) d\tau} x$ we have that $\pi = (\Phi, \sigma)$ is a linear skew-product semiflow on $E = X \times \Theta$.

Definition 1.3 A linear skew-product semiflow $\pi = (\Phi, \sigma)$ on $E = X \times \Theta$ is said to be **stable** if there exists $N > 0$ such that

$$\|\Phi(\theta, t)\| \leq N, \quad \forall (\theta, t) \in \Theta \times \mathbb{R}_+$$

Definition 1.4 A linear skew-product semiflow $\pi = (\Phi, \sigma)$ on $E = X \times \Theta$ is **uniformly exponentially stable** if there are $N, \nu > 0$ such that

$$\|\Phi(\theta, t)\| \leq Ne^{-\nu t}, \quad \forall (\theta, t) \in \Theta \times \mathbb{R}_+$$

Example 1.2 Let $\lambda \in \mathbb{R}_+$. Consider the linear skew product semiflow $\pi_\lambda = (\Phi_\lambda, \sigma)$

where $\Phi_\lambda(\theta, t) = e^{-\lambda t} \Phi(\theta, t)$ and $\pi = (\Phi, \sigma)$ is the linear skew product semiflow given in example 1.1. For $\lambda > \alpha$, π_λ is uniformly exponentially stable and for

$\lambda \in [0, \alpha]$ and $\theta_0(\tau) = \alpha$, for all $\tau \geq 0$ we have :

$$\|\Phi_\lambda(\theta_0, t)X\| = \begin{cases} \|X\|, & \text{if } \lambda = \alpha \\ e^{\alpha-\lambda} \|X\| & \text{if } \lambda < \alpha \end{cases}, \text{ so } \pi_\lambda \text{ is not uniformly exponentially stable.}$$

Let $C_b(\mathbb{R}_+, X)$ be the linear space of all bounded continuous functions $u: \mathbb{R}_+ \rightarrow X$ and

$$C_0(\mathbb{R}_+, X) = \left\{ u \in C_b(\mathbb{R}_+, X) : \lim_{t \rightarrow \infty} u(t) = 0 \right\}$$

$$C_{00}(\mathbb{R}_+, X) = \left\{ u \in C_b(\mathbb{R}_+, X) : u(0) = \lim_{t \rightarrow \infty} u(t) = 0 \right\}$$

Endowed with sup - norm $\|u\| = \sup_{t \geq 0} \|u(t)\|$, $C_0(\mathbb{R}_+, X)$ and $C_b(\mathbb{R}_+, X)$ are Banach spaces.

Let $C_c(\mathbb{R}_+, X)$ be the space of all continuous functions $u: \mathbb{R}_+ \rightarrow X$ with compact support contained in $(0, \infty)$.

Denote by F the linear space of all Bochner measurable functions $u: \mathbb{R}_+ \rightarrow X$ identifying the functions which are equal almost everywhere. For every $p \in [1, \infty)$ the linear space

$$L^p(\mathbb{R}_+, X) = \left\{ u \in F : \int_0^\infty \|u(t)\|^p dt < \infty \right\}$$

is a Banach space with respect to the norm:

$$\|u\|_p := \left(\int_0^\infty \|u(t)\|^p dt \right)^{\frac{1}{p}}$$

2. Perron conditions for exponential stability

Definition 2.1 We say that a strongly continuous linear skew-product semiflow $\pi = (\Phi, \sigma)$ is $(C_c(\mathbb{R}_+, X), B(\Theta, C_b(\mathbb{R}_+, X)))$ - **stable** if:

(i) the linear operator $P: C_c(\mathbb{R}_+, X) \rightarrow B(\Theta, C_b(\mathbb{R}_+, X))$

$$P(u)(\theta)(t) = \int_0^t \Phi(\tau(\theta, \tau), t - \tau) u(\tau) d\tau$$

is well defined .

(ii) there exist $K > 0$ such that :

$$\|Pu\|_{B(\Theta, C_b(\mathbb{R}_+, X))} \leq K \|u\|, \forall u \in C_c(\mathbb{R}_+, X)$$

Definition 2.2 Let $E(R_+, X) \in \{C_{00}(R_+, X), C_b(R_+, X)\}$, we say that a strongly continuous linear skew-product semiflow $\pi = (\Phi, \sigma)$ is

$(E(R_+, X), B(\Theta, C_b(R_+, X)))$ -**stable** if $S : E(R_+, X) \rightarrow B(\Theta, C_b(R_+, X))$ with:

$$S(u)(\theta)(t) = \int_0^t \Phi(\sigma(\theta, \tau), t - \tau)u(\tau) d\tau$$

is well defined .

Proposition 2.1 If π is $(E(R_+, X), B(\Theta, C_b(R_+, X)))$ -**stable**, then S is a bounded operator.

Proof

Let $(u_n) \subset E(R_+, X)$, $u \in E(R_+, X)$ and $f \in B(\Theta, C_b(R_+, X))$ such that:

$$u_n \xrightarrow{n \rightarrow \infty} u \text{ in } E(R_+, X) \text{ and } S(u_n) \xrightarrow{n \rightarrow \infty} f \text{ in } B(\Theta, C_b(R_+, X))$$

We have that:

$$S(u_n)(\theta)(t) \xrightarrow{n \rightarrow \infty} f(\theta)(t), \quad (\forall)(\theta, t) \in \Theta \times R_+$$

Using $u_n \xrightarrow{n \rightarrow \infty} u$ uniformly on R_+ we obtain

$$\begin{aligned} S(u_n)(\theta)(t) &= \int_0^t \Phi(\sigma(\theta, \tau), t - \tau)u_n(\tau) d\tau \xrightarrow{n \rightarrow \infty} \int_0^t \Phi(\sigma(\theta, \tau), t - \tau)u(\tau) d\tau = \\ &= S(u)(\theta)(t), (\forall)(\theta, t) \in \Theta \times R_+ \end{aligned}$$

We have $f = S(u)$, so S is a closed linear operator and S is bounded.

Proposition 2.2 Let $\pi = (\Phi, \sigma)$ be a linear skew-product semiflow on $E = X \times \Theta$. If there are $t_0 > 0$ and $c \in (0, 1)$ such that $\|\Phi(\theta, t_0)\| \leq c$ for $\forall \theta \in \Theta$, then π is uniformly exponentially unstable.

Proof

Let $M \geq 1$ and $\omega > 0$ be given by definition 1.2. and ν be a positive number such that $c = e^{-\nu t_0}$.

Let $\theta \in \Theta$ be fixed. For $t \geq 0$ there are $n \in \mathbb{N}$ and $r \in [0, t_0]$ such that $t = nt_0 + r$. Then we obtain :

$$\|\Phi(\theta, t)\| \leq \|\Phi(\sigma(\theta, nt_0), r)\| \|\Phi(\theta, nt_0)\| \leq Me^{\omega t_0} e^{-\nu nt_0} \leq Ne^{-\nu t}$$

Where $N = Me^{(\omega + \nu)t_0}$. So, π is uniformly exponentially stable.

Theorem 2.1 Let $\pi = (\Phi, \sigma)$ be a strongly continuous linear skew-product semiflow on $E = X \times \Theta$. Then the following assertions are equivalent:

- (i) π is uniformly exponentially stable;
- (ii) π is $(C_b(\mathbb{R}_+, X), B(\Theta, C_b(\mathbb{R}_+, X)))$ -stable;
- (iii) π is $(C_{00}(\mathbb{R}_+, X), B(\Theta, C_b(\mathbb{R}_+, X)))$ -stable;
- (iv) π is $(C_{00}(\mathbb{R}_+, X), B(\Theta, C_{00}(\mathbb{R}_+, X)))$ -stable;

Proof (i) \Rightarrow (ii) Let $N, \nu > 0$ with:

$$\|\Phi(\theta, t)\| \leq Ne^{-\nu t} \quad \forall (\theta, t) \in \Theta \times \mathbb{R}_+.$$

Let $u \in C_b(\mathbb{R}_+, X)$. For all $(\theta, t) \in \Theta \times \mathbb{R}_+$ we have

$$\|S(u)(\theta)(t)\| \leq \int_0^t Ne^{-\nu(t-\tau)} \|u(\tau)\| d\tau \leq N \|u\| \int_0^t e^{-\nu s} ds \leq \frac{N}{\nu} \|u\|$$

So $S(u) \in B(\Theta, C_b(\mathbb{R}_+, X))$.

It follows that π is $(C_b(\mathbb{R}_+, X), B(\Theta, C_b(\mathbb{R}_+, X)))$ -stable.

The implication (ii) \Rightarrow (iii) is obvious, (i) \Rightarrow (iv) is a simple exercise, (iv) \Rightarrow (iii) is obvious.

Suppose that (iii) holds and there is $K > 0$ such that

$$\|P_\theta u\| \leq K \|u\| \tag{2.1}$$

for all $(u, \theta) \in C_0(\mathbb{R}_+, X) \times \Theta$.

Consider $M \geq 1$ and $\omega > 0$ given by definition 1.2.

Let $\theta \in \Theta$ and $x \in X$. If $\alpha: \mathbb{R}_+ \rightarrow [0, 2]$ is a continuous function with the support contained in $(0, 1)$ and with the property:

$$\int_0^1 \alpha(s) ds = 1$$

Then we consider the function

$$u: \mathbb{R}_+ \rightarrow X, \quad u(t) = \alpha(t) \Phi(\theta, t) x$$

So $u \in C_0(\mathbb{R}_+, X)$ and $\|u\| = \sup_{t \in [0, 1]} \|u(t)\| \leq 2Me^\omega \|x\|$

For $t \geq 1$ we have that:

$$P(u)(\theta)(t) = \int_0^t \alpha(s) \Phi(\sigma(\theta, s), t-s) \Phi(\theta, s) x ds = \Phi(\theta, t) x$$

Then using, (2.1) we have:

$$\|\Phi(\theta, t) x\| \leq \|P(u)\| \leq 2KM e^\omega \|x\| \quad (2.2)$$

For $t \in [0, 1]$ we have :

$$\|\Phi(\theta, t)\| \leq M e^\omega \quad (2.3)$$

So, denoting by $L = (2K + 1) M e^\omega$ and using (2.2) and (2.3) we obtain:

$$\|\Phi(\theta, t)\| \leq L$$

for all $(\theta, t) \in \Theta \times R_+$

Consider $\nu = \frac{e}{4LK}$ and $\varphi: R_+ \rightarrow R_+$, $\varphi(t) = \int_0^t s e^{-\nu s} ds$

The function φ is strictly increasing on R_+ with $\lim_{t \rightarrow \infty} \varphi(t) = \frac{1}{\nu^2}$

So, we can choose $\delta > 0$ such that $\varphi(\delta) > \frac{1}{2\nu^2}$.

Let $\theta \in \Theta$ and $x \in X$. Define the function

$$\nu: R_+ \rightarrow X, \nu(t) = t e^{-\nu t} \Phi(\theta, t) x$$

Then $\nu \in C_{00}(R_+, X)$ and

$$\|\nu\| \leq L \|x\| \sup_{t \geq 0} t e^{-\nu t} = \frac{L}{\nu e} \|x\|$$

We observe that $P(\nu)(\theta)(\delta) = \varphi(\delta) \Phi(\theta, \delta) x$ and it follows that :

$$\|\Phi(\theta, \delta) x\| \leq 2\nu^2 \varphi(\delta) \|\Phi(\theta, \delta) x\| \leq 2\nu^2 \|P(\nu)\| \leq 2\nu \frac{LK}{e} \|x\| = \frac{1}{2} \|x\|$$

It results that: $\|\Phi(\theta, \delta)\| \leq \frac{1}{2}$ for all $\theta \in \Theta$. From proposition 2.2 we have that π is uniformly exponentially stable.

Definition 2.3 Let $\rho \in (1, \infty)$. We say that a strongly continuous linear skew-product semiflow $\pi = (\Phi, \sigma)$ is $(C_c(R_+, X), B(\Theta, C_b(R_+, X)))$ - **p-stable** if:

(i) the linear operator $P: C_c(R_+, X) \rightarrow B(\Theta, C_b(R_+, X))$

$$P(u)(\theta)(t) = \int_0^t \Phi(\tau(\theta, \tau), t-\tau) u(\tau) d\tau$$

is well defined .
(ii) there exist $K>0$ such that :

$$\|Pu\|_{B(\Theta, C_b(R_+, X))} \leq K \|u\|_p, \forall u \in C_c(R_+, X)$$

Definition 2.4 Let $p \in (1, \infty)$, we say that a strongly continuous linear skew-product semiflow $\pi = (\Phi, \sigma)$ is $(L^p(R_+, X), B(\Theta, C_b(R_+, X)))$ -**stable** if $Q : L^p(R_+, X) \rightarrow B(\Theta, C_b(R_+, X))$ with:

$$Q(u)(\theta)(t) = \int_0^t \Phi(\sigma(\theta, \tau), t - \tau) u(\tau) d\tau$$

is well defined .

Proposition 2.3 If π is $(L^p(R_+, X), B(\Theta, C_b(R_+, X)))$ -stable , then Q is a bounded operator.

Theorem 2.2 Let $p \in (1, \infty)$ and $\pi = (\Phi, \sigma)$ be a strongly continuous linear skew-product semiflow on $E = X \times \Theta$. Then the following assertions are equivalent:

- (i) π is uniformly exponentially stable;
- (ii) π is $(L^p(R_+, X), B(\Theta, C_b(R_+, X)))$ - stable;
- (iii) π is $(C_c(R_+, X), B(\Theta, C_b(R_+, X)))$ -p- stable;

Proof

(i) \Rightarrow (ii) Let $N, \nu > 0$ such that:

$$\|\Phi(\theta, t)\| \leq N e^{-\nu t} \quad \forall (\theta, t) \in \Theta \times R_+ .$$

Let $u \in L^p(R_+, X)$ and $p' = \frac{p}{p-1}$. For all $(\theta, t) \in \Theta \times R_+$ we have:

$$\begin{aligned} \|Q(u)(\theta)(t)\| &\leq N \int_0^t e^{-\nu(t-\tau)} \|u(\tau)\| d\tau \leq \\ &\leq N \left(\int_0^t e^{-\nu p'(t-\tau)} d\tau \right)^{1/p'} \left(\int_0^t \|u(\tau)\|^p d\tau \right)^{1/p} \leq \frac{N}{(\nu p')^{1/p'}} \|u\|_p \end{aligned}$$

So $Q(u) \in B(\Theta, C_b(R_+, X))$

- (ii) \Rightarrow (iii) follows from proposition 2.3.
- (iii) \Rightarrow (i) see [7], theorem 2.4.4.

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